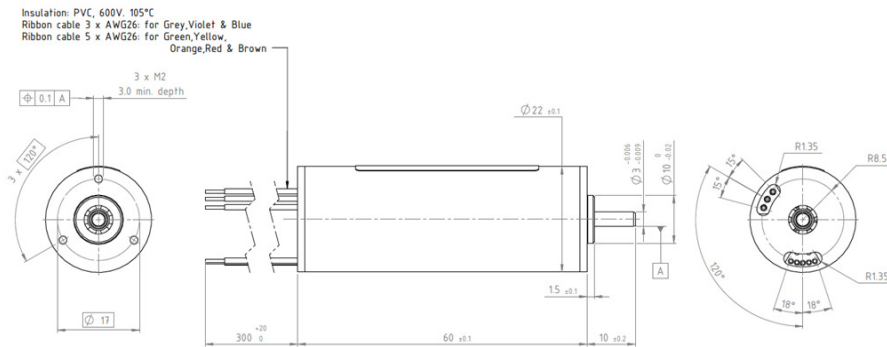


22ECP60 Ultra EC™

2 pole

Ø22mm

120W



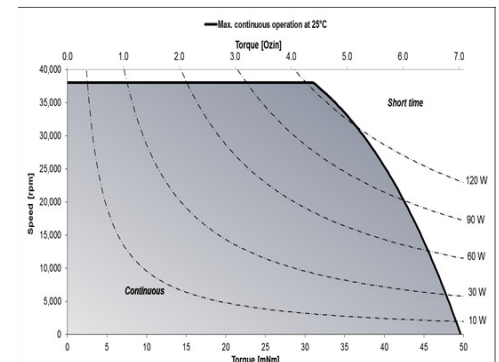
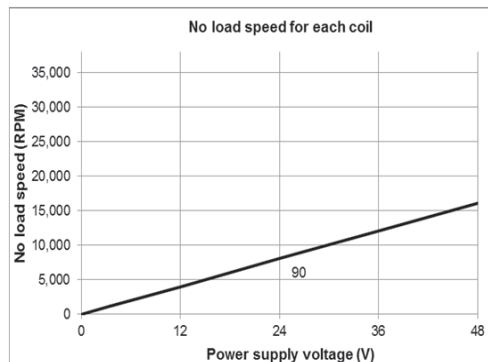
Dimensions in mm

22ECP60 8B - \*\*

Electrical Data	**	90	
1 Nominal Voltage	$U_N$	24	Volt
2 Optimization Direction	-	Symmetrical	-
3 No-Load Speed	$n_0$	8,050	rpm
4 Typical No-Load Current	$I_0$	40	mA
5 Max Continuous Mechanical Power (@25°C)	$P_{max}$	120	W
6 Max Continuous Current	$I_{e,max}$	1.8	A
7 Max Continuous Torque	$M_{e,max}$	50.5 (7.16)	mNm (oz-in)
8 Back EMF Constant	$K_E$	2.96	V/1000 rpm
9 Torque Constant	$k_M$	28.3	mNm/A
10 Motor Regulation	$R/k^2$	3.0	$10^3/Nms$
11 Motor Regulation	$k/R^{1/2}$	18.3 (2.6)	$mNm/W^{1/2}$ (oz-in/ $W^{1/2}$ )
12 Internal Resistance - phase to phase	$R_I$	2.38	ohms
13 Line to Line Resistance at Connectors	$R_L$	2.47	ohms
14 Inductance Phase to Phase	$L$	0.48	mH
15 Mechanical Time Constant	$t_m$	1.0	ms
16 Electrical Time Constant	$t_e$	0.20	ms

General Data			
17 Maximum Motor Speed	$n_{max}$	38000	rpm
18 Ambient Working Temperature Range	-	-30 to + 100 (-22 to + 212)	°C (°F)
19 Ambient Storage Temperature Range	-	-40 to + 100 (-40 to + 212)	°C (°F)
20 Ball Bearings Preload	-	5.50	N
21 Axial Static Force w/o Shaft Support (max)	-	34	N
22 Maximum Winding Temperature	-	125 (257)	°C (°F)
23 Thermal Resistance	$R_{th1}/R_{th2}$	1/8.4	°C/W
24 Thermal Time Constant	$t_w$	1100	s
25 Weight	-	140 (4.94)	g (oz)
26 Rotor Inertia	$J$	3.5	$g.cm^2$
27 Hall Sensor Electrical Phasing	-	120	Electrical °

with hall effect sensors	
Wire	Description
Grey	Phase 1
Violet	Phase 2
Blue	Phase 3
Green	3.5 to 27V DC
Yellow	GND
Orange	Sensor 1
Red	Sensor 2
Brown	Sensor 3



V10112016