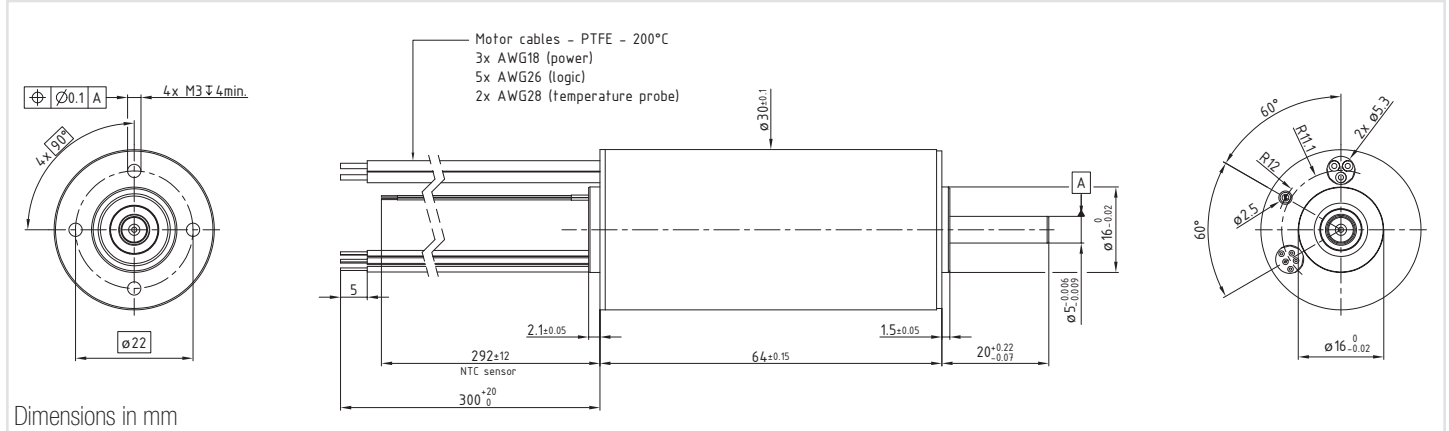


30ECT64 Ultra EC™

4 pole

∅30mm

187W



Dimensions in mm

30ECT64 - 10B - **

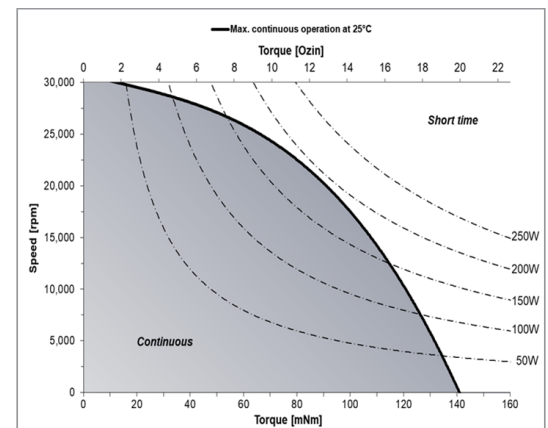
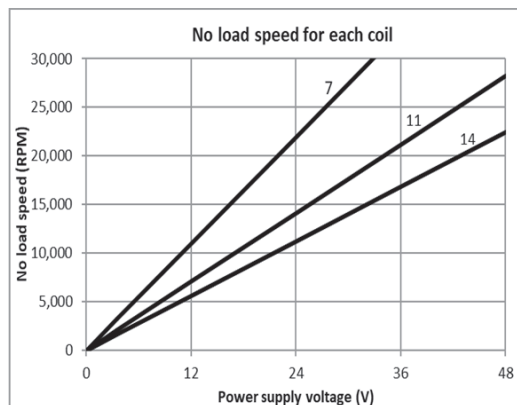
Electrical Data	**	7	11	14	
1 Nominal Voltage	U_N	24	36	48	Volt
2 Optimization Direction	-	Symmetrical	Symmetrical	Symmetrical	-
3 No-Load Speed	n_0	21,930	21,150	22,425	rpm
4 Typical No-Load Current	I_0	575	425	300	mA
5 Max Continuous Mechanical Power (@25°C)	P_{max}	187.0	187.0	187.0	W
6 Max Continuous Current	$I_{e max}$	12.9	8.1	6.5	A
7 Max Continuous Torque	$M_{e max}$	136 (19.26)	134 (18.98)	133 (18.84)	mNm (oz-in)
8 Back EMF Constant	K_E	1.10	1.74	2.14	V/1000 rpm
9 Torque Constant	k_M	10.5	16.6	20.5	mNm/A
10 Motor Regulation	R/k^2	0.57	0.59	0.60	$10^3/Nms$
11 Motor Regulation	$k/R^{1/2}$	41.8 (5.92)	41.2 (5.85)	40.8 (5.78)	$mNm/W^{1/2}$ (oz-in/ $W^{1/2}$)
12 Internal Resistance - phase to phase	R_i	0.064	0.162	0.252	ohms
13 Line to Line Resistance at Connectors	R_L	0.079	0.177	0.267	ohms
14 Inductance Phase to Phase	L	0.015	0.036	0.058	mH
15 Mechanical Time Constant	t_m	1.6	1.6	1.7	ms
16 Electrical Time Constant	t_e	0.23	0.22	0.23	ms

General Data

17 Maximum Motor Speed	n_{max}		30,000		rpm
18 Ambient Working Temperature Range	-		-30 to +100 (-22 to +212)		°C (°F)
19 Ambient Storage Temperature Range	-		-40 to +100 (-40 to +212)		°C (°F)
20 Ball Bearings Preload	-		13.5		N
21 Axial Static Force w/o Shaft Support (max)	-		134		N
22 Maximum Winding Temperature	-		150 (302)		°C (°F)
23 Thermal Resistance	R_{th1}/R_{th2}		0.9/7		°C/W
24 Thermal Time Constant	t_w		1,327		s
25 Weight	-		263 (9.28)		g (oz)
26 Rotor Inertia	J		28.00		$g \cdot cm^2$
27 Hall Sensor Electrical Phasing	-		120		Electrical °

* Available without hall sensor

With hall effect sensors	
Wire	Description
Grey	Phase 1
Violet	Phase 2
Blue	Phase 3
Green	VDC (4 to 24V)
Yellow	GND
Orange	Sensor 1
Red	Sensor 2
Brown	Sensor 3
Black	Thermistor (+)
White	Thermistor (-)



V03062018