



Dimensions in mm.

Electrical Data	Symbol	30ECT64-10B-xxx.01			Unit
		7	11	14	
1 Nominal Voltage	U_N	24	36	48	Volt
2 Optimization Direction	-	Symetrical	Symetrical	Symetrical	-
3 No-Load Speed	n_0	21,930	21,150	22,425	rpm
4 Typical No-Load Current	I_0	575	425	300	mA
5 Max Continuous Mechanical Power (@25°C)	P_{max}	187.0	187.0	187.0	W
6 Max Continuous Current	$I_{e,max}$	12.9	8.1	6.5	A
7 Max Continuous Torque	$M_{e,max}$	136 (19.26)	134 (18.98)	133 (18.84)	mNm (oz-in)
8 Back EMF Constant	k_E	1.10	1.74	2.14	V/1000 rpm
9 Torque Constant	k_M	10.5	16.6	20.5	mNm/A
10 Motor Regulation	R/k^2	0.6	0.6	0.6	10 ³ /Nms
11 Motor Regulation	$k/R^{1/2}$	41.8 (5.92)	41.2 (5.85)	40.8 (5.78)	mNm/W ^{1/2} (oz-in/W ^{1/2})
12 Internal Resistance - phase to phase	R_i	0.06	0.16	0.25	ohms
13 Line to Line Resistance at Connectors	R_L	0.08	0.18	0.27	ohms
14 Inductance Phase to Phase	L	0.02	0.04	0.06	mH
15 Mechanical Time Constant	τ_m	1.6	1.6	1.7	ms
16 Electrical Time Constant	τ_e	0.23	0.22	0.23	ms

General Data				
17 Maximum Motor Speed	n_{max}		30,000	rpm
18 Ambient Working Temperature Range	-		-30 to + 100 (-22 to + 212)	°C (°F)
19 Ambient Storage Temperature Range	-		-40 to + 100 (-40 to + 212)	°C (°F)
20 Ball Bearings Preload	-		13.5	N
21 Axial Static Force w/o Shaft Support (max)	-		134	N
22 Maximum Winding Temperature	-		150 (302)	°C (°F)
23 Thermal Resistance	R_{th}		0.9/7	°C/W
24 Thermal Time Constant	τ_w		1,327	s
25 Weight	-		263 (9.28)	g (oz)
26 Rotor Inertia	J		28.00	g-cm ²
27 Hall Sensor Electrical Phasing*	-		120	Electrical °

*Available without hall sensor

Wire	Description
Gray	Phase 1
Violet	Phase 2
Blue	Phase 3
Green	4 to 24V DC
Yellow	GND
Orange	Sensor 1
Red	Sensor 2
Brown	Sensor 3
Black	Thermistor (+)
White	Thermistor (-)

with hall effect sensor

